Section 2.3 (Product and Quotient Rules and Higher Order Derivatives)

We covered the sum and difference rules for derivatives in the previous section. The product and quotient rules are a little more involved (see book for proofs)...

1. Product Rule:
$$\frac{d}{dx} [f(x)g(x)] = f(x)g'(x) + g(x)f'(x)$$
 (note: not the same as a composition function)
--- 1st times the derivative of the 2nd + 2nd times the derivative of the 1st ---
2. Quotient Rule: $\frac{d}{dx} \left[\frac{f(x)}{g(x)} \right] = \frac{g(x)f'(x) - f(x)g'(x)}{[g(x)]^2}$
--- low-d-hi minus hi-d-low over low squared ---

Examples: Find the following derivatives

 $h(x) = (5x^2 - 2x)(3x + 4)$ $y = 4x^3 \sin(x)$ $y = 3x \sin(x) - 4 \cos(x)$ $f(x) = x^3 \sin(x) \cos(x)$

h(x) =
$$\frac{5x+2}{x^2-7}$$
 $y = \frac{6-(1/x)}{x+9}$ h(x) = $\frac{x^3-4x}{5}$

Knowing the derivatives of sin and cos allows us to find the derivatives of the remaining trigonometric functions. <u>Example</u>: Use the quotient rule to find the derivative of tan(x) Derivatives of trigonometric functions:

$\frac{d}{dx}\sin(x)=\cos(x)$	$\frac{d}{dx}\cos(x) = -\sin(x)$	$\frac{d}{dx}\tan(x) = _$
$\frac{d}{dx}\csc(x) = -\csc(x)\cot(x)$	$\frac{d}{dx}$ sec(x) = sec(x)tan(x)	$\frac{d}{dx}\cot\left(\mathbf{x}\right) = -\csc^2(\mathbf{x})$

Examples: Find the derivatives of the following...

$$y = 3x^5 - \cot(x)$$
 $y = x^2 \csc(x)$ $y = \frac{1 - \cos(x)}{\sin(x)} = \csc(x) - \cot(x)$

--- Note that much of the work in finding derivatives is in simplifying after differentiation ---

Similarly to finding velocity with the derivative of the position function (velocity = change in position over time), we can obtain acceleration using the derivative of the velocity function (acceleration = change in velocity over time).

Position: s(t) Velocity: v(t) = s'(t) Acceleration: a(t) = v'(t) = s''(t)

The function a(t) is the second derivative of s(t) --- This is the derivative of the first derivative (other higher-order derivatives follow)

Application Example: (Review example 10 in the book) Paul Blart is travelling at a rate of 22.5 mph (33 feet per second) on his Segway when the brakes are applied. The position function of the Segway is $s(t) = -4.3t^2 + 22.5t$, where s is measured in feet and t in seconds. Use this function to complete the table...



t	0	1	2	3	4
s(t)					
v(t)					
a(t)					